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Workflows as UML Activity Diagrams: Analytical Methods for Control-Flow Verification

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Abstract

A workflow is a directed graph that depicts a business process. It consists of tasks linked together by AND and XOR connectors, and is usually drawn as a Petri Net or a UML Activity Diagram; the latter notation has gained in popularity in recent years. Workflows sometimes suffer from behavioral defects such as deadlock, lack of synchronization, and interminable looping. Here we present new analytical results useful for verifying the control flow in workflows represented as UML Activity Diagrams. We make use of the notion of 'corresponding pair' and focus on loop-free structures, allowing connectors to form non-nested and overlapping patterns. The analysis can be extended to workflows with loops. To clarify the significance of our results, we provide illustrations of theoretical and practical interest.

Keywords: Workflow, Business process, Verification, Control flow, Analytical method

1. Introduction: A workflow is used by a business organization to perform a specific business function, and is usually depicted as a directed graph consisting of tasks linked together by AND and XOR connectors. A newly created workflow might contain defects that cause control flow errors such as deadlock, lack of synchronization and interminable looping, and dataflow errors such as missing data, redundant data and lost data. It is therefore necessary to verify it before employing it in practice. The verification problem is known to be difficult; no existing algorithm or software package does a completely satisfactory job.

Workflows are often represented as Petri Nets [2]; their control flow can be verified by the Woflan package [10]. In recent years, other graphical formalisms such as UML Activity Diagrams [4], BPMN [7] and Metagraphs [3] have gained in popularity. UML Activity Diagrams have the advantage of being convenient for both control flow and data flow analysis [8]. New analytical results that pertain to this formalism for detecting control flow errors in non-nested

(unstructured) workflows are of topical interest. Our approach here has two distinctive features: a) we provide, for the first time, control-flow verification procedures based on analytical results for a formalism other than Petri Nets; b) our analysis makes use of the interesting notion of 'corresponding pair' [5,6]. We focus on the loop-free case, but our results can be extended to workflows that contain loops and those that employ connectors other than AND and XOR [1].

1.1 Illustrative Example: MHA Inc. manufactures modern household appliances. It wants to increase its production capacity and build a new factory within its premises. It floats a tender inviting construction firms to apply for the project. A firm responds to the tender call, but since the processing of the application by MHA might take time, it formulates in parallel a budget estimate and plan of work. These are submitted to MHA and are considered for approval once the tender application has been accepted. The UML Activity Diagram G for handling the applications is shown in Figure 1. G is non-nested and has two case instances, *i.e.*, control flows in G in two different ways depending on the choice of the outgoing path at the XOR split. In the first, which contains tasks a, b, d and e, the firm's tender application is rejected. The AND join never gets activated because task c is not part of the case instance and does not get performed. Although tasks b and d get done unnecessarily, this gives a realistic picture of how the firm would function. The second relates to the acceptance of the tender application and consists of tasks a, b, c, d and f, here the AND join does get activated.

2. Analysis of the Loop-free Case: Let *G* be a loop-free workflow with XOR and AND split/join connectors. *G* has the following structural characteristics:

- All splits and joins are binary. This causes no loss in generality, since, for example, a ternary split (join) can always be broken up into two binary splits (joins).
- The START connector s has no incoming edge and one outgoing edge, and the END connector r has one incoming edge and no outgoing edge.
- Tasks can follow one another without intervening connectors, and a connector can follow another connector.
- *G* has no simple structural defects such as dangling nodes; there is a directed path from *s* to every node and from every node to *r*.

• 1	a	the construction		
2		firm submits a		
		tender application		
$ \begin{array}{c} a \\ b \\ c \\ c \\ c \\ f \\ 6 \\ 6 \\ 6 \\ 6 \\ 6 \\ 6 \\ 6 \\ 6 \\ 6 \\ 6$	b c d			
		and plan of work		
		for approval		
	e	MHA informs the firm that its tender application has been rejected		
	f	the firm gets approval from		
		MHA to begin the		
		construction job		
Figure 1: Non-nested loop-free workflow				

 Deadlock, lack of synchronization and inactive AND joins (see below) are the only errors that can arise when *G* is processed.

Definition 1: A corresponding pair (cp) is a pair (X,Y) of connectors in G, where X is a split connector, Y is a join connector, and there are two outgoing paths starting at X that meet at Y but not at any predecessor of Y. CP refers to the set of cps of a given workflow. A cp (X, Y) is a strong corresponding pair (scp) if there is no join connector Z that is a predecessor of Y in Gsuch that (X,Z) is a cp. SCP refers to the set of scps in G. Different pairs of outgoing paths from the split connector X meet at different join connectors Y, Z, W, ..., for the first time. Typically, one of these pairs defines an scp, while the others define cps. In overlapping structures (see Figures 3,4), two cps with X as the first element can both be scps. A weak corresponding pair (wcp) is a cp that is not an scp. WCP refers to the set of wcps in G. So CP= $SCP \cup WCP$, and $SCP \cap WCP = \Phi$ (empty

set). A cp (X,Y) is *proper* if X and Y are connectors of the same type (either both XOR or both AND); otherwise it is *improper*.

These definitions generalize the ones given in [5, 6]; 'corresponding pair' there is the same as 'strong corresponding pair' here. We bring in the additional concept of 'weak corresponding pair' to achieve a more careful analysis of the theoretical properties of workflows.

Example 1: For the workflow of Figure 1, $CP = \{(2,4), (2,5), (3,5)\}$, $SCP = \{(2,4), (3,5)\}$, $WCP = \{(2,5)\}$. Clearly, two outgoing paths from connector 2 meet for the first time at connector 4, and two outgoing paths from connector 3 meet for the first time at connector 5. In addition, two

other outgoing paths from connector 2, namely the paths 2-3-5 and 2-4-5, meet for the first time at connector 5. Since connector 4 is a predecessor of connector 5, (2,5) is in *WCP* and not in *SCP*. The cps (2,4) and (3,5) are proper, but the cp (2,5) is improper. Thus in this example *SCP* consists only of proper cps, but *WCP* contains only one cp and it is improper. \Box

Definition 2: A *lack of synchronization error* arises when both incoming edges at an XOR join are simultaneously active. A *deadlock error* arises when: i) not all incoming edges at an AND join are simultaneously active; and, ii) flow of control is halted at the AND join so it is not possible to reach the END node. In a *well-behaved* workflow, neither of these errors ever occurs. Sometimes a workflow is well-behaved but an AND join remains inactive in some case instance. From an operational point of view this is not as serious as a deadlock error and might even help to portray a realistic situation, as in Figure 1. But an *inactive AND join* has often been regarded as an undesirable feature as it can lead to unnecessary execution of tasks. A well-behaved workflow is *strongly well-behaved* if no inactive AND joins ever occur.

Example 2: A workflow with a single cp consisting of an AND split and an XOR join suffers from a lack of synchronization error, and one with a single cp consisting of an XOR split and an



AND join suffers from a deadlock error. In the loopfree workflow *G* of Figure 2, $SCP = \{(2,4), (5,7), (6,3)\}, WCP = \{(2,7), (6,7)\}, and (5,7) is the only$ improper cp. There is lack of synchronization at

connector 7 when the left outgoing paths are taken at connectors 2 and 6. If connector 4 is changed to an AND join, there is deadlock at 4. If 4 is changed back to an XOR join, and 5 is changed to an XOR split, G consists entirely of XOR connectors and is strongly well behaved, and all cps are proper. The workflow of Figure 1 is well behaved since control reaches from the START node to the END node in both case instances; it is not strongly well behaved since connector 4 is inactive in one case instance. \Box

Definitions 3: In a *nested* workflow, splits and joins occur in pairs as in nested balanced parentheses. A workflow that is not fully nested is said to be *non-nested*. If the two connectors in a nested pair are of different types, say (AND, XOR) or (XOR, AND), an error will occur. When they are of the same type, they are said to be *matched*, *i.e.*, proper, and for the purpose of our theoretical analysis the matched pairs can be collapsed and omitted from the workflow as these pairs do not give rise to errors. A workflow that is fully nested with matched pairs can be reduced in this way to just the START and END nodes. Given a non-nested workflow *G*, we can get a *reduced* workflow *G* is said to be *non-planar* if there is no way to draw *G* on a plane without crossovers when the START connector is placed at plus infinity (upwards) and the END connector is placed at minus infinity (downwards); *G* is *planar* if it is not non-planar. *G* is *overlapping* if *G* is non-planar and *G* contains a split connector X such that there are at least two scps starting with X. The workflow of Figure 3 is reduced and overlapping.

2.1 Theoretical Results: In the results presented here the notion of corresponding pair (cp) plays an important role because errors such as deadlock and lack of synchronization occur at join connectors, where two different paths merge to form a single path.

Theorem 1: Let *G* be a loop-free workflow. Then: a) if every cp in *CP* is proper then *G* is strongly well-behaved; b) if a lack of synchronization error occurs at an XOR join Y in *G*, then *CP* contains an improper cp (X,Y) of type (AND,XOR); c) if a deadlock error occurs at an AND join Y in *G*, then *CP* contains an improper cp (X,Y) of type (XOR,AND); d) if there is an inactive AND join in a case instance in *G*, then *CP* contains an improper cp of type (AND,XOR).

Proof: a) If G is not strongly well-behaved, there must be an improper cp in CP; otherwise no error conditions can arise. b)–d) Depending on the type of the improper cp, there is a lack of synchronization error, a deadlock error or an inactive AND join. \Box

Example 3: In the loop-free overlapping workflow of Figure 3, $SCP = \{(2,5), (2,6), (3,7), (4,7)\}$, $WCP = \{(2,7)\}$, every cp in *SCP* is proper, but the only cp in *WCP* is improper. The workflow is strongly well-behaved. The overlapping workflow of Figure 4 has the same *SCP* and *WCP* but suffers from deadlock error. Thus Theorem 1(a) does not hold when '*CP*' is changed to '*SCP*'. \Box

Theorem 2: Let G be a loop-free workflow. If SCP contains an improper cp then G is not

strongly well-behaved.

Proof: Let (X,Y) be an improper cp in *SCP*. Suppose (X,Y) is of type (AND,XOR), and consider a workflow instance that contains the connectors X and Y. If both incoming paths at Y are active then there is a lack of synchronization error at Y. An attempt at merging the signals in the two paths by means of a path (W,Z) of type (XOR,AND), as shown in Figure 5, makes Z inactive when the right hand outgoing path is selected at W; moreover, (X,Y) ceases to be in *SCP*. If W is an XOR split at any other position, or W is an AND split belonging to some other instance, Z is inactive and G is not strongly well-behaved. When (X,Y) is of type (XOR,AND), the only way to make G strongly well-behaved is by means of an overlap as shown in Figure 6, where (W1,Z1) and (W2,Z2) are both of type (AND,XOR); but then the cp (X,Y) is no longer in *SCP*. \Box



Example 4: The workflow of Figure 7 is well-behaved but not strongly well-behaved, since the AND join 9 is inactive in two of the three case instances. In one of them the left outgoing edge is chosen at connector 2, and in the other the right outgoing edge is chosen at connector 3. Here $SCP = \{(2,7), (3,8$

(4,11), (5,9), (6,10)}, and (4,11) and (6,10) are improper. Thus Theorem 2 does not hold when 'strongly well-behaved' is changed to 'well-behaved'. The overlapping workflow shown in Figure 3 is strongly well-behaved, although *WCP* contains the improper cp (2,7).



Thus Theorem 2 fails to hold when 'SCP' is changed to 'CP'. \Box

Theorem 3: Let G be a loop-free workflow. If G suffers from a lack of synchronization error but no other errors, then *SCP* contains an improper cp of type (AND,XOR).

Proof: Suppose a lack of synchronization error occurs at the XOR connector Y (see Figure 5). Then by Theorem 1(b) there must be a cp (X,Y) of type (AND,XOR) in *CP*.

Suppose there is an edge (W,Z) as shown, so that (X,Y) is not in *SCP*. If W is of type AND, then *SCP* contains an improper cp (W,Y) of type (AND,XOR). If W is of type XOR and Z is of type AND, there is either no error or an inactive AND join. So both W and Z must be of type XOR. But then the cp (X,Z) is of type (AND, XOR) and is contained in *SCP*. Note that if there is a connector Y' between W and Z, then Y' can only be an AND join; this will lead to an inactive AND join in some case instances. \Box

Example 5: Even when there is a cp of type (AND,XOR) in *SCP*, no lack of synchronization error might result. In Figure 7, the cps (4,11) and (6,10) only cause an inactive AND join. \Box

Stronger results sometimes hold when a loop-free workflow can be drawn on the plane.



Theorem 4: Let the workflow G be loop-free, planar and strongly wellbehaved. Then every cp in CP is proper. If G is also reduced, then the connectors in G are all of the same type (either all XOR or all AND).

Proof: Since *G* is loop-free and planar, it can be drawn on the plane with no crossovers. It will then have a mesh-like structure with polygonal regions (see Figure 8). *G* is also strongly well-behaved, so all nested pairs in *G* must be matched; we can therefore assume *G* is reduced. In Figure 8, the X's are splits and the Y's are joins. It is easily checked that if a single Y is of type AND, then all splits and joins must be of type AND; otherwise there is an error or an inactive AND join. Similarly, if a single Y is of type XOR, all splits and joins must be of type XOR. Thus the connectors are either all AND or all XOR. \Box

Example 6: Theorem 4 does not hold for overlapping structures. The workflow of Figure 3 is strongly well-behaved, but the cp (2,7) in *CP* is improper. \Box

Theorem 5: Let the workflow G be loop-free and planar. Suppose every cp in SCP is proper.

a) If WCP contains an improper cp of type (XOR,AND) then G suffers from deadlock error.

b) If *WCP* contains an improper cp of type (AND,XOR) then *G* has an inactive AND join.

Proof: a) In Figure 5, let (X,Y) represent an improper cp of type (XOR,AND). Since all cps in

SCP are proper, W must be an AND split and Z an XOR join. This immediately implies that when the left outgoing path is taken at X, there will be a deadlock error at Y. The same error occurs when there is more than one such path (W, Z) in parallel. The only way to resolve the problem would be by an overlap as shown in Figure 6, but G is by assumption planar.

b) Let (X,Y) in Figure 5 represent an improper cp of type (AND,XOR). Then W must be an XOR split and Z an AND join. If we take the right path at W, an inactive AND join occurs at Z.

Theorem 6: Let the workflow *G* be loop-free and planar.

- Given condition No Conclusion SCP WCP Contains an improper Deadlock or inactive AND join 1 scp of type (XOR,AND) Lack of synchronization Contains an improper 2 or inactive AND join of scp type (AND,XOR) Contains an improper 3 Deadlock All scps are proper wcp of type (XOR,AND) Contains an improper 4 All scps are proper Inactive AND join wcp of type (AND,XOR) Strongly well-behaved; when reduced, the 5 All scps are proper All wcps are proper connectors are either all XOR or all AND **Table 1: Loop-free Planar Workflows**
- a) If *SCP* contains an improper cp of type (XOR,AND), then *G* suffers from deadlock error or has an inactive AND join.
 - b) If SCP contains an improper cp of type (AND,XOR), then G suffers from lack of synchronization error or has an inactive AND join.

Proof: See the proofs of Theorems 2 and 5. \Box

These results can be very useful in verification (see the summary in Table 1).

Remark 1: Table 1 does not apply to overlapping structures. The basic overlapping structure has three splits and three joins (see Figure 3). Allowing each split and join to be either AND or XOR, there are a total of 64 cases. Of these, one has AND connectors only and another has XOR connectors only. Five of the remaining 62 are well behaved and the remaining 57 are erroneous (Figure 4 shows one of them), but not all are distinct. Figure 3 is the standard example of a strongly well behaved overlapping structure. \Box

2.2 Verification Procedure for Loop-free Workflows: We now proceed to the verification procedure for loop-free workflows, assuming that the workflow, if it is overlapping, has the basic structure of three splits and three joins as shown in Figures 3 and 4.

Step 1: Using a graph algorithm for detecting loops, determine whether the workflow *G* is loop-free. If yes, proceed to Step 2, else exit.

Step 2: If G contains mismatched nested pairs then G is not well	ll-behaved; give error message
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/* input: a loop-free workflow G */	and exit. Else collapse the nested pairs, get
{ initialize SCP, WCP, CP to empty sets;	reduced workflow G' and proceed to next
for every split node X in workflow G do {	step.
find every join Y reachable from X along two	Step 3: Determine SCP and WCP for G'
outgoing paths such that the two paths meet at Y for	using the algorithm <i>findSCP&WCP</i> (see Table 2).
the first time; let <i>XCJ</i> be this set of joins;	Step 4: Check whether there is a split
determine the subset of joins XSJ in XCJ which have	connector X in G' such that two different cps
no predecessors in XCJ;	(X,Z) and (X,W) are both contained in SCP.
$XCP = \{ (X,Y) \mid Y \in XCJ \};$	If yes, then <i>G</i> ' must be overlapping; compare against known cases and see if it is (strongly)
$XSCP = \{ (X,Y) \mid Y \in XSJ \};$	well-behaved. Otherwise, G' is planar. Using
$XWCP = XCP - XSCP; CP = CP \cup XCP;$	Table 1, find out whether G' is (strongly)
$SCP = SCP \cup XSCP; WCP = WCP \cup XWCP; \}$	well-behaved. In either case, output an appropriate message and exit.
}	3. Workflows with Loops: The analysis can
Table 2: Algorithm findSCP&WCP	be extended to workflows with loops. In this

case, it is not possible to define a consistent predecessor-successor relationship between connectors, so *SCP* can not be defined. However, all the cps in CP can be identified. Such a workflow will be valid only when each loop contains an XOR split for control to flow out and an XOR join for control to flow in. In addition, AND joins in loops must satisfy certain conditions, which are not specified here owing to lack of space.

4. Conclusion: We have derived analytical results and described simple verification procedures for loop-free workflows consisting of AND and XOR connectors. These methods are adequate for verifying most situations that arise in practice or are cited in the technical literature. Various other types of connectors have been proposed in [1], *e.g.*, inclusive ORs. The theoretical results and verification procedures can be extended to these connectors, as well as to workflows with loops. Since both the control flow and the data flow must be verified in a workflow, it would be advisable to model a workflow as a Document Driven Activity Diagram [8, 9]. The ultimate objective is to make use of the notion of 'corresponding pair' and develop a comprehensive verification procedure capable of detecting both control flow and data flow errors.

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